

D.C. Generator. Chapter - 1

- 1) The armature of a d.c. machine is made of \_\_\_\_\_  
(i) silicon steel (ii) wrought iron.  
(iii) cast steel (iv) soft iron.
- 2) A 4 pole d.c. machine has \_\_\_\_\_ magnetic ccts.  
(i) 2 (ii) 8  
(iii) 4 (iv) none of the above.
- 3) The greatest eddy current loss occurs in the \_\_\_\_\_ of a d.c. machine.  
(i) field poles (ii) yoke.  
(iii) commutating pole (iv) armature.
- 4) The commutator pitch for a simplex lap winding is equal to.  
(i) number of poles of the machine.  
(ii) pole pairs.  
(iii) 1  
(iv) none of the above.
- 5) In a d.c. machine, the number of commutator segments is equal to.  
(i) number of conductors (ii) twice the number of poles.  
(iii) number of coils (iv) none of the above.
- 6) An 4 pole simplex lap winding will have \_\_\_\_\_ parallel paths.  
(i) 8 (ii) 4  
(iii) 32 (iv) 16

⑦ A 6-pole lap wound generator has 300 conductors. The e.m.f induced per conductor being 5V. The generated voltage of the generator is \_\_\_\_\_.

- (i) 60V. (ii) 1500V.  
 (iii) 350V. (iv) ~~250V.~~

⑧ A shunt generator delivers 195A at a terminal p.d. of 250V. The  $R_a = 0.02\Omega$ ,  $R_{sh} = 50\Omega$ . What is the value of generated emf.?

- (i) 246V. (ii) 270V  
 (iii) ~~254V.~~ (iv) 282V.

⑨ If  $W_c$  is the constant loss and  $R_a$  is the armature resistance of a d.c. generator, then load current  $I_L$  corresponding to maximum efficiency is

- (i)  $I_L = \sqrt{\frac{R_a}{W_c}}$  (ii)  $I_L = \frac{W_c}{R_a}$   
 (iii)  $I_L = \frac{R_a}{\sqrt{W_c}}$  (iv)  ~~$I_L = \sqrt{\frac{W_c}{R_a}}$~~

⑩ From question number 8 what is the value of copper losses?

- (i) 825W. (ii) ~~2050W.~~  
 (iii) 1025W. (iv) 960W.

⑪ A 4 pole, lap wound d.c shunt generator has an armature winding consisting of 220 turns each of  $0.004\Omega$ . The armature resistance is

- (i)  $0.5\Omega$  (ii)  $1\Omega$   
 (iii)  $0.025\Omega$  (iv)  ~~$0.055\Omega$ .~~



# D.C. Generator. Chapter-II.

## Armature Reaction and Commutation.

- 1) In a d.c. generator armature reaction is produced by
  - (i) the field current
  - (ii) armature current.
  - (iii) both field and armature current.
  - (iv) none of the above.
  
- 2) Armature reaction is increased when
  - (i) the field current increases.
  - (ii) the armature current decreases.
  - (iii) the armature current increases.
  - (iv) none of the above.
  
- 3) When a d.c. generator carries no armature current
  - (i) M.N.A coincides with G.N.A.
  - (ii) M.N.A is behind G.N.A.
  - (iii) M.N.A is ahead of G.N.A.
  - (iv) none of the above.
  
- 4) In order to have sparkless commutation, the brushes should be placed
  - (i) along G.N.A
  - (ii) along M.N.A.
  - (iii) along G.N.A or M.N.A
  - (iv) none of the above.
  
- 5) Flux distribution due to armature reaction causes the M.N.A in a generator to
  - (i) remain stationary
  - (ii) move in the dir<sup>n</sup> of rotation.
  - (iii) move opposite to the dir<sup>n</sup> of rotation.
  - (iv) none of the above.

6) In a d.c. generator the effect of armature reaction on the main pole flux is to

(i) reduce it. (ii) distort it.

(iii) both reduce and distort it.

(iv) reverse it.

7) During commutation, the coil undergoing commutation \_\_\_\_\_ by the brush.

(i) remains short-circuited.

(ii) remains open-circuited.

(iii) either (i) or (ii).

(iv) none of the above

8) The current-time graph for ideal commutation is

(i) a straight line (ii) parabola.

(iii) hyperbola.

(iv) none of the above.

9) The commutation period is of the order of

(i)  $\frac{1}{10}$  second.

(ii)  $\frac{1}{50}$  second.

(iii)  $\frac{1}{20}$  second.

(iv)  $\frac{1}{500}$  second.

10) The reactance voltage in a d.c. shunt generator depends upon

(i) armature current (ii) field current.

(iii) both (i) & (ii)

(iv) neither (i) nor (ii)



Characteristics.

1) The field winding of a d.c. shunt machine usually carries \_\_\_\_\_ of the rated current of the machine.

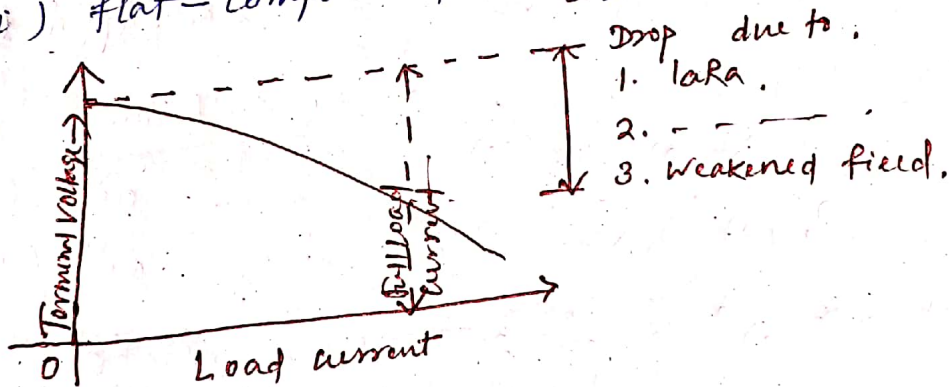
- (i) 2% to 5%
- (ii) 15% to 20%
- (iii) more than 20%
- (iv) less than 0.5%

2) D.C. machines which are subjected to abrupt changes of load are provided with \_\_\_\_\_.

- (i) interpole windings
- (ii) compensating windings
- (iii) equalizers
- (iv) copper brushes

3) Fig. 1 shows the external characteristic of \_\_\_\_\_ generator.

- (i) Over-compounded
- (ii) Series
- (iii) flat-compounded
- (iv) Shunt



4) Referring to Fig. 1. the voltage drop at no. 2 is due to \_\_\_\_\_.

- (i) friction
- (ii) armature reaction
- (iii) field circuit
- (iv) none of the above

5) The O.C.C. of a d.c. generator is also called its \_\_\_\_\_ characteristic.

- (i) magnetic
- (ii) internal
- (iii) external
- (iv) performance

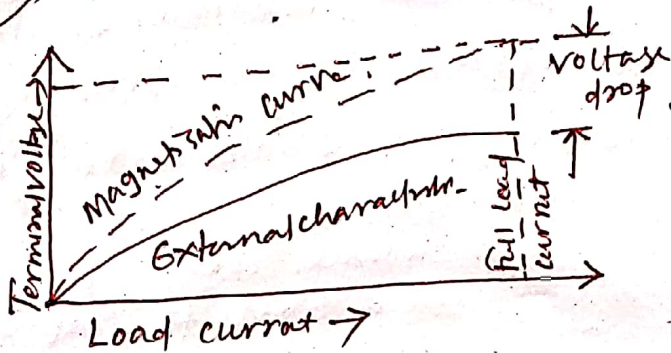
6) Fig. 2 shows the external characteristics of a \_\_\_\_\_ generator.

(i) shunt.

(ii) flat-compounded.

(iii) series.

(iv) over-compounded.



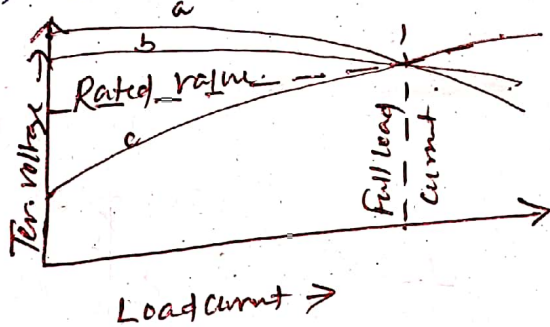
7) Fig. 3, curve C represents the external characteristics of a \_\_\_\_\_ generator.

(i) compound.

(ii) separately-excited.

(iii) shunt

(iv) none of the above.



8) The line representing the critical resistance of a d.c. generator \_\_\_\_\_ its O.C.C.

(i) intersects

(ii) runs parallel to.

(iii) just touches

(iv) none of the above.

9) Which of the following generator provides approximately const. voltage from no-load to full-load.

(i) series

(ii) shunt.

(iii) flat compounded

(iv) over-compounded.

10) A shunt generator gives its greatest voltage at \_\_\_\_\_

(i) no-load.

(ii) full-load.

(iii) half full-load

(iv) none of the above.

# 1- $\phi$ TRANSFORMER

- 1) A transformer will work on \_\_\_\_\_  
a)  a-c. only      b)  d-c. only.  
c)  a-c as well as d-c.      d)  none of the above.
- 2) The primary and secondary of a transformer are coupled \_\_\_\_\_  
a)  electrically.      b)  magnetically.  
c)  both (a) & (b)      d)  none of the above.
- 3) A transformer transfers electrical energy from primary to secondary usually with change of \_\_\_\_\_  
a)  frequency      b)  power.  
c)  voltage      d)  time period.
- 4) Calculate the core-area required for a 1600 KVA, 6600/440V, 50Hz, single phase core-type power transformer. Assume a maximum flux density of 1.2 Wb/m<sup>2</sup> and induced voltage per turn of 30V.  
a)  975 cm<sup>2</sup>      b)  1100 cm<sup>2</sup>  
c)  1125 cm<sup>2</sup>      d)  1224 cm<sup>2</sup>.
- 5) The no-load input power to a transformer is practically equal to \_\_\_\_\_ loss in the transformer.  
a)  iron      b)  copper.  
c)  eddy current      d)  none of the above.
- 6) The voltage transformation ratio is given by \_\_\_\_\_  
a)   $N_1/N_2$       b)   $E_1/E_2$   
c)   $N_2/N_1$       d)   $I_2/I_1$
- 7) In equivalent circuit of a transformer on no-load. The element  $R_0$  accounts for \_\_\_\_\_  
a)  core loss      b)  copper loss.  
c)  magnetic leakage loss      d)  none of the above.



## D.C. motor Chapter-2

- 4) By putting controller resistance in series with the armature of a d.c. motor, we can obtain speed.
- (a) above the normal speed only.
  - (b) below the normal speed only.
  - (c) above as well as below the normal speed.
  - (d) none of the above
- 5) The difference between no-load and full-load speed of a d.c. shunt motor is of the order of.
- a) 25%
  - b) 1%
  - c) 10%
  - d) 50%

## Chapter-3, Testing of D.C. ~~motor~~ machines

- 1) The efficiency of a large d.c. machine is not determined by direct loading because.
- a) it is difficult to provide means for operating a large machine under load.
  - b) it is an expensive method.
  - c) it requires the application of load.
  - d) all the above.
- 2) In a d.c. machine, windage loss is proportional to.
- a) speed
  - b) cube of speed.
  - c) square of speed
  - d) none of the above.
- 3) A d.c. machine has maximum efficiency near \_\_\_\_\_
- a) half full load
  - b) full-load.
  - c) twice the full load
  - d) No-load.



- 1) The back e.m.f in a d.c. motor. \_\_\_\_\_
- opposes the applied voltage.
  - aids the applied voltage
  - aids the armature current.
  - none of the above
- 2) The value of back e.m.f ( $E_b$ ) in d.c. motor is maximum at \_\_\_\_\_
- full load
  - no-load.
  - half full load
  - none of above.
- 3) A 440V d.c. shunt motor has an armature resistance of  $0.8\Omega$  and a field resistance of  $200\Omega$ . Find the back e.m.f when giving an output of  $7.46\text{ kW}$  at  $85\%$  efficiency.
- $222.4\text{ V}$
  - $425.8\text{ V}$ .
  - $312.6\text{ V}$
  - $392.7\text{ V}$ .
- 4) A 250V d.c. shunt motor takes a total current of  $20\text{ A}$ . Resistance of shunt field winding is  $200\Omega$  and that of armature is  $0.3\Omega$ . What is the current in the armature.
- $9.65\text{ A}$
  - $11.25\text{ A}$ .
  - $18.75\text{ A}$
  - $16.62\text{ A}$ .
- 5) A 220V d.c. shunt motor takes a total current of  $80\text{ A}$  and runs at  $800\text{ r.p.m.}$  Resistance of shunt field is  $50\Omega$  and that of armature is  $0.1\Omega$ . The iron and friction losses amount to  $1600\text{ W}$ . What is the driving power of the motor.
- $16050\text{ W}$
  - $14500\text{ W}$ .
  - $12600\text{ W}$ .
  - $18500\text{ W}$ .
- 6) D.C. motor converts \_\_\_\_\_ into \_\_\_\_\_.
- mechanical energy; electrical energy
  - Chemical energy; electrical energy
  - Solar energy; Chemical energy.
  - Electrical energy; Mechanical energy.

- 7) The shaft torque ( $T_{sh}$ ) in a d.c. motor is less than total armature torque ( $T_a$ ) because of \_\_\_\_\_ in the motor.
- (i) Cu losses      (ii) field losses.  
~~(iii) iron and friction losses~~ (iv) none of the above.
- 8) Which motor has the best speed regulation.
- (i) Series.      (ii) Cumulatively - Compounded.  
~~(iii) Shunt~~      (iv) Differentially - Compounded.
- 9) When a d.c. series motor will overspeed.
- (i) the load is increased.  
(ii) the field is opened.  
(iii) the armature ckt is opened.  
~~(iv) load is removed.~~
- 10) For the same rating, which motor has the least starting torque.
- (i) Compound      (ii) Series.  
~~(iii) Shunt~~      (iv) none of the above

Chapter - 2, Speed control of D.C. motors.

- 1) A d.c. motor runs at 1725 r.p.m. at full-load and 1775 r.p.m. at no-load. The speed regulation is.
- (i) 4.7%      ~~(ii) 2.9%~~  
(iii) 7.6%      (iv) 1.5%
- 2) The speed of a d.c. motor can be controlled by changing.
- (i) flux      (ii) armature ckt resistance.  
(iii) applied voltage ~~(iv) all of the above.~~
- 3) We can control speed by flux control method of speed control of a d.c. shunt motor.
- ~~(i) above the normal speed only.~~  
(ii) below the normal speed only.  
~~(iii) above as well as below the normal speed.~~  
(iv) none of the above.